

# Sample Transfer & Manipulation

## Section Nine



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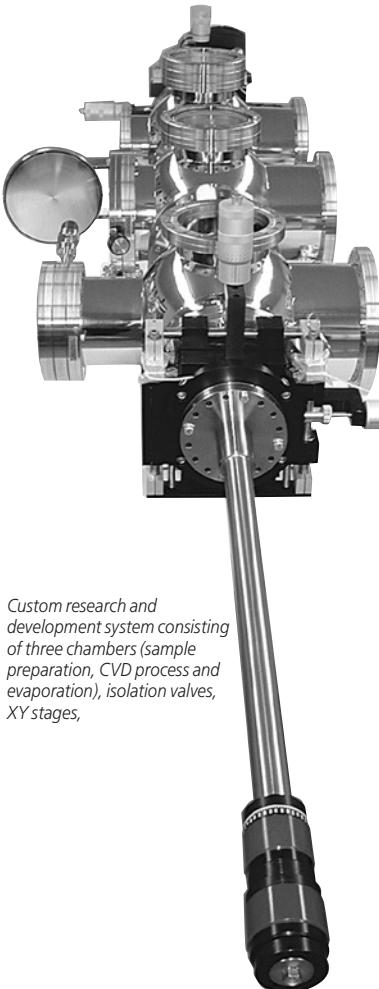
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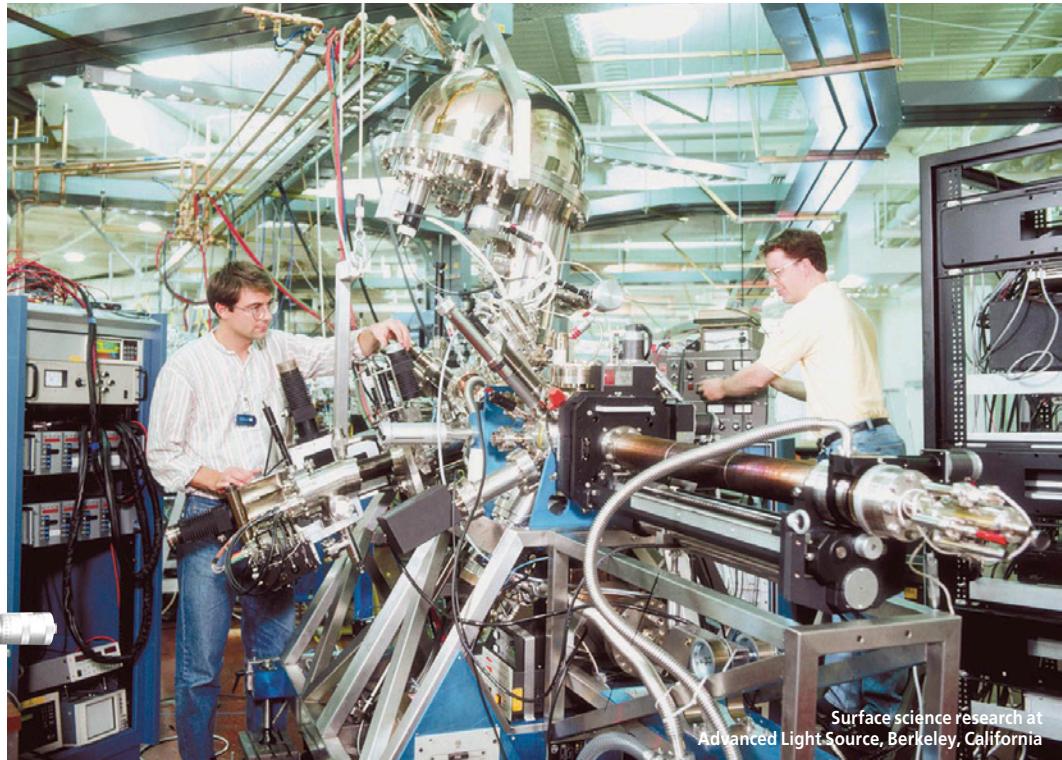
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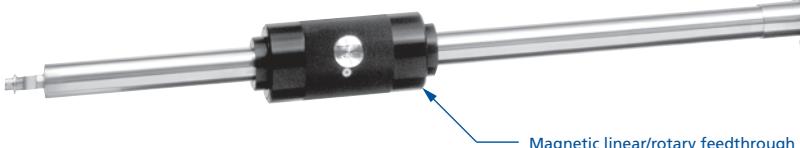
*Custom research and development system consisting of three chambers (sample preparation, CVD process and evaporation), isolation valves, XY stages,*



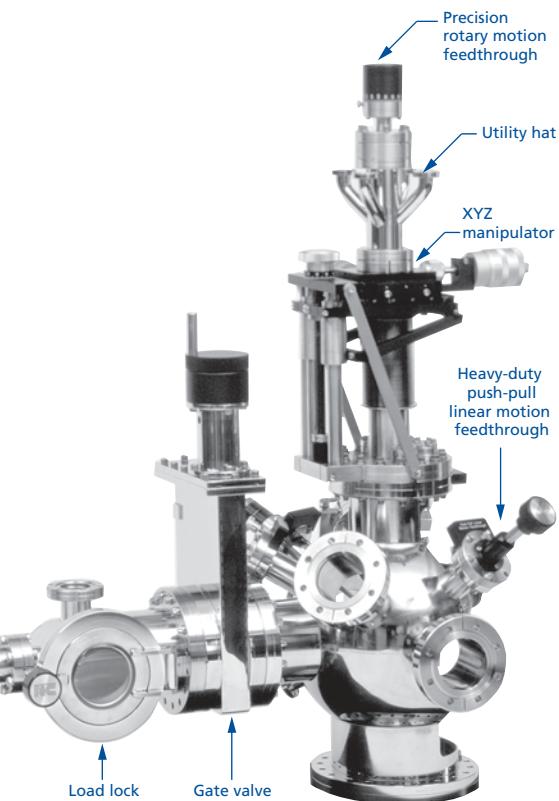
**Surface science research at Advanced Light Source, Berkeley, California**

Nor-Cal Products offers the researcher complimentary devices for sample transfer and positioning in ultra-high vacuum systems.

Combined with our vacuum chambers, load locks, gate valves, all-metal valves, feedthroughs, viewports, frames and roughing accessories, we can provide a complete turn-key research system. Each standard component can readily be customized to meet specific requirements, such



*All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.*



# Sample Transfer & Manipulation

## Terminology

SECTION 9.1

### XYZ Manipulator

The XYZ manipulator is a 3-axis (X,Y,Z) positioning device which is typically mounted outside the vacuum chamber for most applications. A welded bellows provides a flexible vacuum curtain. The X axis passes in front of the vertical, mechanical structure, or "backframe," with the Y axis moving to and away from the backframe. The Z axis is perpendicular to the X and Y axes and moves up and down directly against the vacuum pressure differential. The polar axis is the same as the Z axis.

The limit of X and Y travel is normally a circular pattern with range indicated as a vector sum. This means a  $\pm .50$  inch (12.7mm) range of X and Y allows the polar axis to be moved anywhere inside a 1.00 inch (25.4mm) diameter circle. The sum of the X and Y vectors is limited to .50 inch (12.7mm). Square pattern XY stages are available as options on some models.

### Z Translator

A translator is a single axis positioning device, utilizing a bellows as a vacuum seal. Referred to as a "Z only" stage, this axis is normally perpendicular to the chamber. This causes the Z axis to work directly against the force from the pressure differential.

### XY Stage

The XY stage provides the X and Y axes only. No Z motion is available.

### Polar Rotation

The polar axis is the same as the Z axis. Rotation about the polar axis is commonly achieved by mounting a rotary feedthrough at the center of the traveling flange of a manipulator or translator. This degree of freedom can also be achieved with a differentially pumped rotary seal.

### Azimuthal Axis

The azimuthal axis is perpendicular to the polar axis. Sample azimuthal rotation refers to rotation of the sample about an axis normal to the sample face and perpendicular to the polar axis.

### Flip Motion

Flip motion is the changing of an axis normal to the sample face from parallel (or coaxial) to the polar axis to coaxial with the azimuthal axis. The range of this change of axis may be 90°, 180° or full 360°.

### Tilt Motion

Tilt refers to changing the polar axis with respect to the X, Y and Z axes. This is usually done at the traveling flange of a 3-axis manipulator or other exterior mounting stage. Tilt range is often limited by the bellows ID and the OD of the probe passing through the bellows. The maximum angle practical is about  $\pm 7^\circ$ . When used in this manner, translation in X, Y and (slightly) Z will occur with adjustment of the It angle. Tilt stages are available in single or dual axis units.

### Sample Transfer & Heating

Sample transfer may reduce heating performance at high temperatures. The ideal transfer system for heating the sample to the highest temperatures should use thin sample plates made of appropriate material placed as close to the heater as possible. Thick, high mass, sample plates reduce thermal response and lower peak heating temperatures.

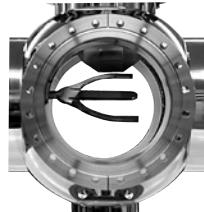
### Sample Transfer & Cooling

Sample transfer may reduce cooling performance at low temperatures. The ideal transfer system for cooling the sample to the lowest temperatures should use thin, highly conductive, sample plates that contact the dewar with a large surface area. Thick, high mass, sample plates reduce thermal response and reduce peak cooling performance.

### Transfer Components

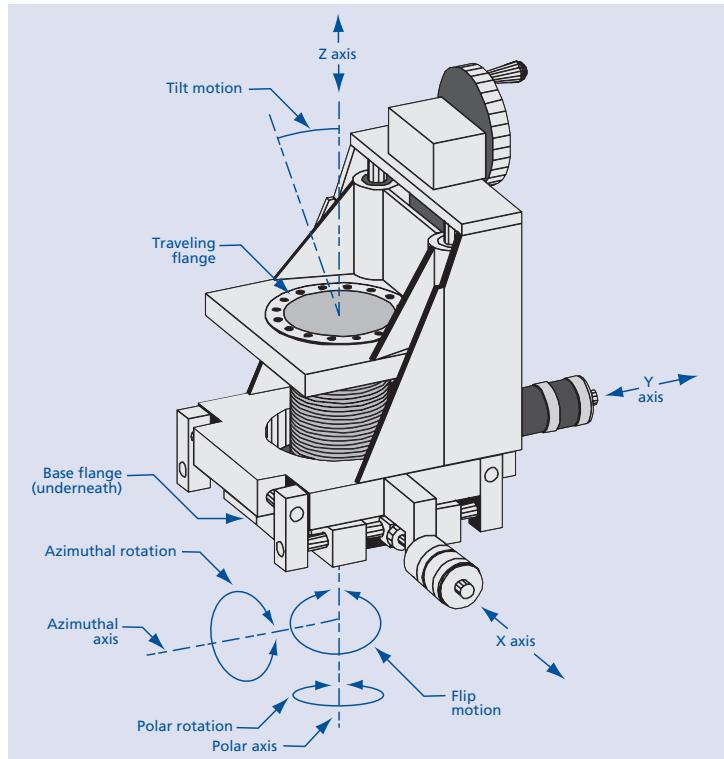
**Sample Platen** - the transferable plate that holds the sample

**Sample Fork** - attaches to a transfer arm from the load-lock and holds the sample platen



Sample transfer fork

**Sample Dock** - attaches to a work station (manipulator) and holds the platen for processing or positioning the sample



### Fork & Dock Configurations

**Axial Fork** - a sample fork with the plane of the sample platen face orthogonal to the axis of the transfer arm on which the fork is mounted

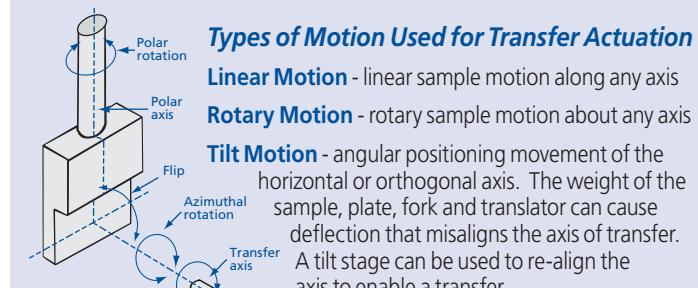
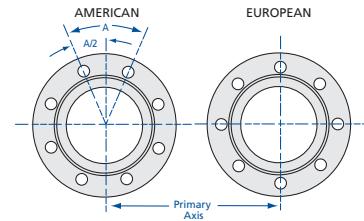
**Radial Fork** - a sample fork with the plane of the sample platen face parallel to the axis of the transfer arm on which the fork is mounted

**Axial Dock** - a sample dock with the plane of the sample platen face orthogonal to the axis of the manipulator on which the dock is mounted

**Radial Dock** - a sample dock with the plane of the sample platen face parallel to the axis of the manipulator to which the dock is mounted.

### Bolt Pattern Orientation

Our components are manufactured with the primary axis straddling adjacent bolt holes on the mounting flange (American standard). Most components can be furnished with the axis passing through a bolt hole axis (European standard) on request. Some equipment is field adjustable.

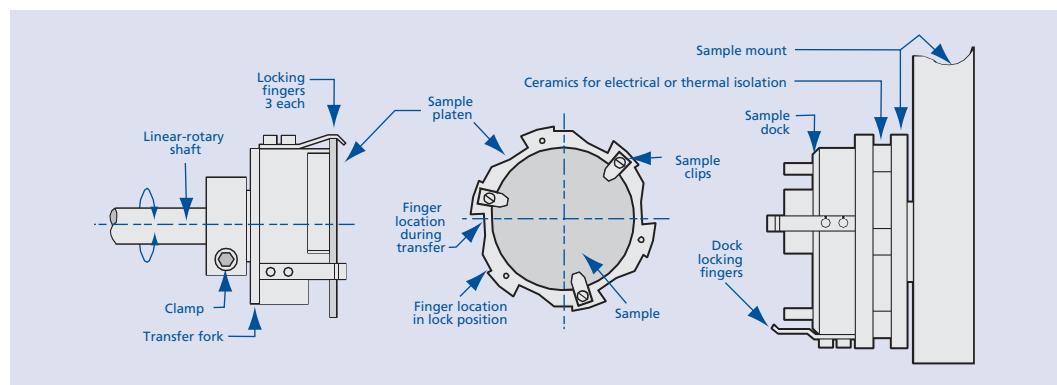
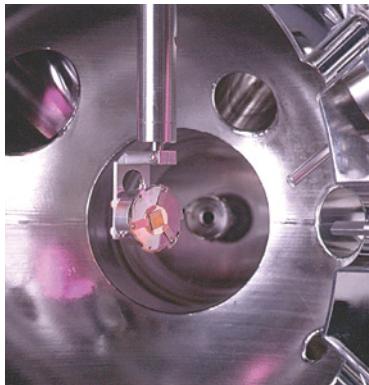


### Types of Motion Used for Transfer Actuation

**Linear Motion** - linear sample motion along any axis

**Rotary Motion** - rotary sample motion about any axis

**Tilt Motion** - angular positioning movement of the horizontal or orthogonal axis. The weight of the sample, plate, fork and translator can cause deflection that misaligns the axis of transfer. A tilt stage can be used to re-align the axis to enable a transfer



### Sample Transfer System

This sample transfer system uses thin (.040 inch) sample plates with six sawtooth shaped ramps, profiled on the plate's edge. The sample transfer probe is fitted with a fork consisting of three tab-shaped spring fingers positioned radially on a barrel. The sample plate locks on to the fork by rotating the fork's fingers over three of the six ramps. When the fork is rotated, the locking fingers slide up the ramps to stops. The plate is gripped by the spring fingers, holding it tight to the barrel of the fork.

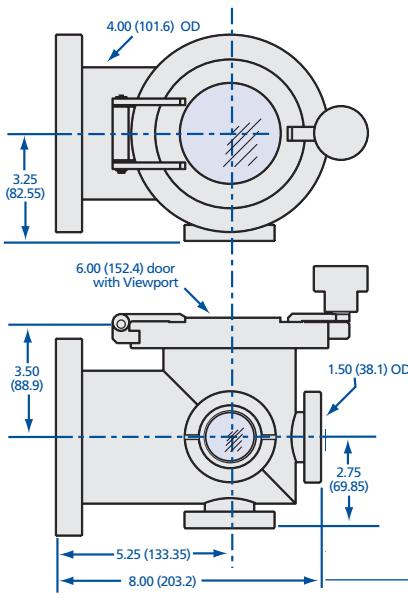
Transferring the sample from the probe fork to a manipulator sample dock is done with a rotary motion. The dock has the same type of locking fingers as the fork. The plate is mated to the dock by orienting it so that the three unused ramps can receive the dock's fingers. Rotating the fork releases the plate at the same time the fingers on the dock grip and lock the plate to the manipulator. This rotary movement makes a smooth sample transfer from the fork to dock and back again.

Nor-Cal Products sample transfer system allows easy, forgiving sample transfer from a rotary/linear feedthrough to the sample dock mounted inside the chamber. Systems are available for sample sizes ranging from 1/2 inch (12.7mm) to 3 inches (76.2mm). Each system includes a dock assembly custom fitted to place the sample on target in your particular chamber, a transfer fork assembly which mounts to a rotary/linear device and two stainless steel sample plates. Molybdenum sample plates are also available. Call for details and pricing.

### Features

- Fast thermal response and greater extremes
- Larger samples may be introduced through smaller ID plumbing
- Excellent sample plane repeatability
- Adapts to most goniometers and precision gearboxes
- Excellent performance for direct and indirect cooling
- Transferable thermocouple, optional
- Transferable intrinsic direct heating
- Five-year guarantee

MODEL NUMBER	SAMPLE OD	MINIMUM PORT OD
<b>STS-050</b>	1/2 (12.7)	1 1/2 (38.1)
<b>STS-100</b>	1 (25.4)	1 1/2 (38.1)
<b>STS-200</b>	2 (50.8)	2 1/2 (63.5)
<b>STS-300</b>	3 (76.2)	4 (101.6)



### Load Lock Chamber

Load lock chambers are an efficient means to introduce a sample into a vacuum chamber without impacting the main chamber vacuum. Load Locks are provided with a six inch CF flange for mounting to the gate valve, a six inch Add-A-Door with 7056 glass viewport, a 2 3/4 inch (70mm) CF flange for attachment of the linear feedthrough, and two 2 3/4 inch (70mm) CF flanges for pumping and gauges. Standard finish is electropolished. Custom sizes and configurations are readily available. Call for pricing.

#### MODEL NUMBER

**LL-600-ADV-150-3**

#### SPECIFICATIONS

##### Construction

Flanges: 304 stainless steel  
Body: 304 stainless steel  
Viewport: 7056 glass  
O-ring: FKM

Temperature range: -20°C to 200°C

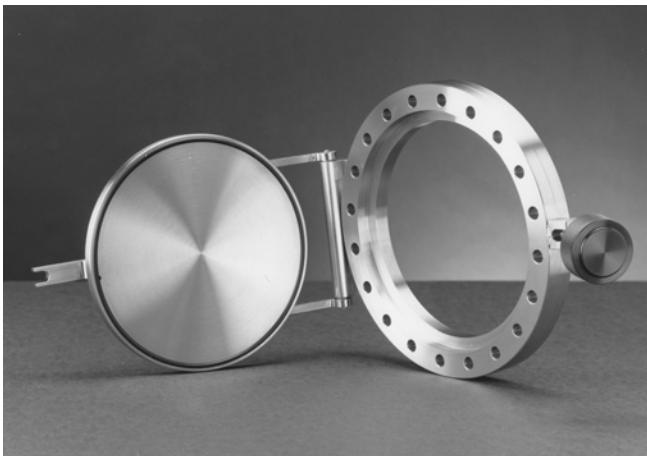
Vacuum range:  $\geq 10^{-8}$  mbar (High vacuum)



# Sample Transfer & Manipulation

## Add-A-Doors

SECTION 9.3



An Add-A-Door can provide easy access to a vacuum system when elastomer seals are acceptable. The hinged, FKM sealed door is quickly bolted to an existing CF (Conflat style) flanged chamber port. The door is opened easily by turning a knurled knob. These doors are available for 2<sup>3</sup>/<sub>4</sub> to 10 inch (70 to 254mm) OD flanges with a solid metal door or with a viewport. The standard finish is electropolish. Custom sizes can be supplied upon request.

### SPECIFICATIONS

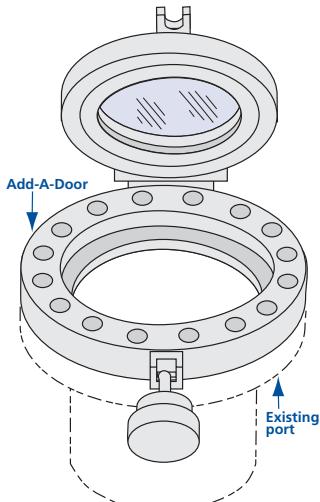
#### Construction

Body: 304 stainless steel  
Flange: 2<sup>3</sup>/<sub>4</sub> to 10 inch (70 to 254mm) CF  
Door: Blank, 7056 glass, or fused silica  
O-ring: FKM standard

**Temperature range:** -20°C to 200°C

**Vacuum range:** ≥ 10<sup>-8</sup> mbar (High vacuum)

### Add-A-Doors



MODEL NUMBER	FLANGE TYPE	A	B
<b>AD-275</b>	2.75 CF	1.380 (35.05)	0.500 (12.70)
<b>AD-450</b>	4.50 CF	2.435 (61.85)	0.687 (17.45)
<b>AD-600</b>	6.00 CF	3.917 (99.49)	0.781 (19.84)
<b>AD-800</b>	8.00 CF	5.875 (149.23)	0.875 (22.23)
<b>AD-1000</b>	10.00 CF	7.875 (200.03)	0.968 (24.59)

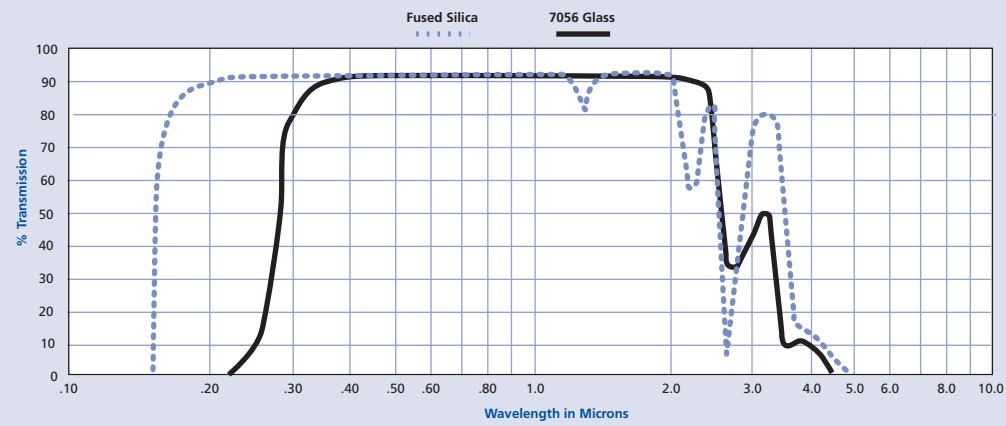
### Add-A-Doors with Viewport – 7056 Glass

MODEL NUMBER	FLANGE TYPE	A	B	C
<b>ADV-450</b>	4.50 CF	2.435 (61.85)	0.687 (17.45)	1.49 (37.85)
<b>ADV-600</b>	6.00 CF	3.917 (99.49)	0.781 (19.84)	2.65 (67.31)
<b>ADV-800</b>	8.00 CF	5.875 (149.23)	0.875 (22.23)	3.88 (98.55)
<b>ADV-1000</b>	10.00 CF	7.875 (200.03)	0.968 (24.59)	5.60 (142.24)

### Add-A-Doors with Viewport – Fused Silica

MODEL NUMBER	FLANGE TYPE	A	B	C
<b>ADVQ-450</b>	4.50 CF	2.435 (61.85)	0.687 (17.45)	1.40 (35.56)
<b>ADVQ-600</b>	6.00 CF	3.917 (99.49)	0.781 (19.84)	2.69 (68.33)
<b>ADVQ-800</b>	8.00 CF	5.875 (149.23)	0.875 (22.23)	3.88 (98.55)
<b>ADVQ-1000</b>	10.00 CF	7.875 (200.03)	0.968 (24.59)	5.38 (136.65)

Viewport Optical Transmission Curves



All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.

# Sample Transfer & Manipulation

## Manipulators, Stages & Translators



### SPECIFICATIONS

#### Construction

Bellows:  $1\frac{7}{8}$  inch (47.63mm) ID  
Base flange: 6 inch (152.4mm) CF, clearance holes with 5 mini flanges  
Traveling flange:  $2\frac{3}{4}$  inch (69.85mm) CF, tapped holes  
Guide rods: Dual  $\frac{3}{4}$  inch (19.05mm) OD hardened stainless steel  
Stage: Aluminum

#### Motion

XY travel:  $\pm \frac{1}{2}$  inch (12.7mm), circular pattern, pre-loaded large drum micrometer stage coupling with .0001 inch (.003) divisions  
Z travel: 2 inch (50.8mm), Acme drive with 2 inch (50.8mm) diameter drive knob (0.10 inch (2.54mm) per turn)

**Operating orientation:** Any; maximum payload 10lbs.(4.54mm) when horizontally mounted

#### Temperature

Maximum bakeout: 150°C, fully assembled  
Operating: 20°C (ambient)

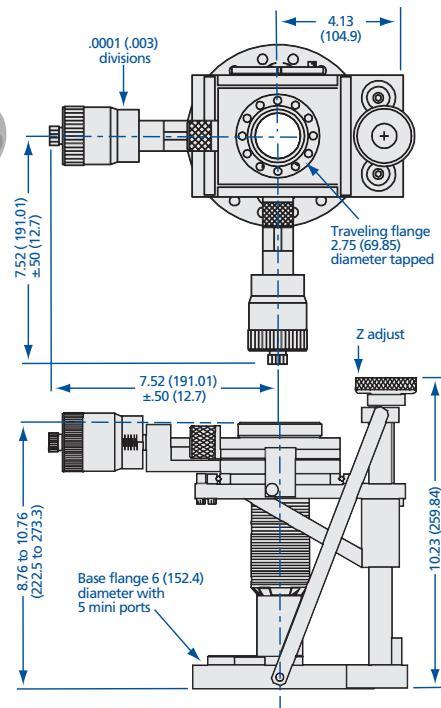
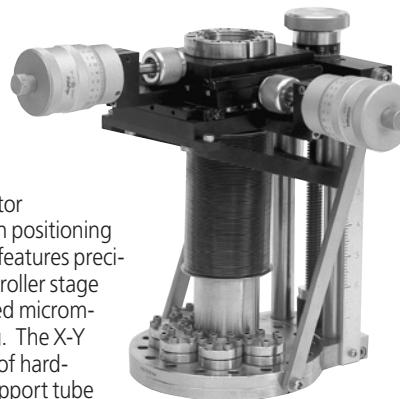
**Vacuum range:**  $\geq 10^{-10}$  mbar (UHV)

**Options:** Support tube

### XYZ Precision Manipulator

The PMXYZ manipulator provides high precision positioning at a minimum cost. It features precision pre-loaded cross-roller stage control with pre-loaded micrometer-to-stage coupling. The X-Y guide system is made of hardened carbon steel. Support tube option includes a  $\frac{3}{4}$  inch (19.05) OD tube and end bearing support. This rigidity on longer rotary shafts.

increases



### XY Stages with Bellows

XY stages are used to provide precise two-axis sample transfer positioning.

### SPECIFICATIONS

#### Construction

Bellows: Edge welded stainless steel  
Base flange: CF, clearance holes  
Traveling flange: CF, tapped holes  
Way bearings: Precision linear

#### Motion

XY travel:  $\pm \frac{1}{2}$  to 1 inch (12.7 to 25.4mm), circular pattern, pre-loaded large drum micrometer stage coupling with 0.0001 inch (.003mm) divisions

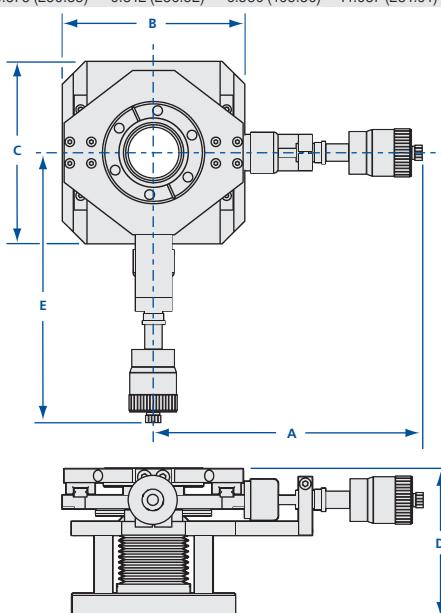
**Operating orientation:** Any; maximum payload 10 lbs(4.54kg) when horizontally mounted

#### Temperature

Maximum bakeout: 150°C, fully assembled  
Operating: 20°C (ambient)

**Vacuum range:**  $\geq 10^{-10}$  mbar (UHV)

All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.



# Sample Transfer & Manipulation

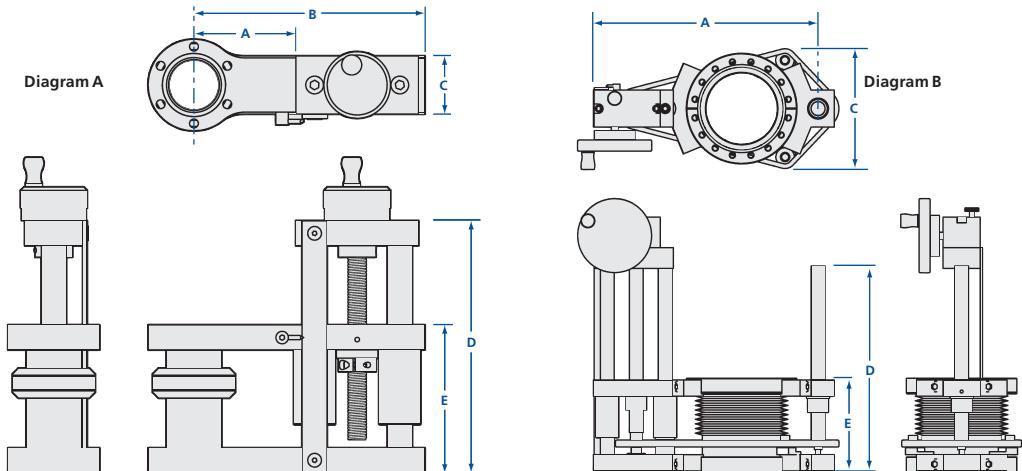
## Manipulators, Stages & Translators

SECTION 9.4

### Z-Translators

Nor-Cal Products Z Translators feature a compact, yet stable, linear motion design suitable for a variety of applications including use with our differentially pumped rotary seals. Z Translators may also be used with feedthrough utility hats and rotary motion feedthroughs.

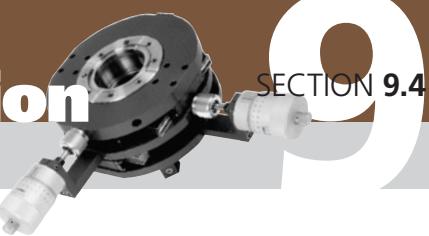
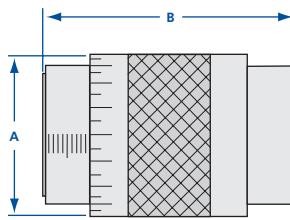
MODEL NUMBER	DIAGRAM.	TRAVELING FLANGE	BELLOWS ID	Z STROKE	BASE FLANGE	A	B	C	MIN.-MAX D & E
MZ-275-153-2	A	2 3/4 (70)	1.53 (38.86)	2	2 3/4 (69.85)	3.060 (77.72)	6.94 (176.28)	1.750 (44.45)	Call
MZ-275-153-4	A	2 3/4 (70)	1.53 (38.86)	4	2 3/4 (69.85)	3.060 (77.72)	6.94 (176.28)	1.750 (44.45)	Call
MZ-275-153-6	A	2 3/4 (70)	1.53 (38.86)	6	2 3/4 (69.85)	3.060 (77.72)	6.94 (176.28)	1.750 (44.45)	Call
MZ-450-188-2	A	2 3/4 (70)	1.88 (47.75)	2	4 1/2 (114.3)	3.250 (82.55)	6.94 (176.28)	1.750 (44.45)	Call
MZ-450-188-4	A	2 3/4 (70)	1.88 (47.75)	4	4 1/2 (114.3)	3.250 (82.55)	6.94 (176.28)	1.750 (44.45)	Call
MZ-450-188-6	A	2 3/4 (70)	1.88 (47.75)	6	4 1/2 (114.3)	3.250 (82.55)	6.94 (176.28)	1.750 (44.45)	Call
MZ-450-250-2	A	4 1/2 (114)	2.50 (63.50)	2	4 1/2 (114.3)	3.250 (82.55)	6.94 (176.28)	1.750 (44.45)	Call
MZ-450-250-4	A	4 1/2 (114)	2.50 (63.50)	4	4 1/2 (114.3)	3.250 (82.55)	6.94 (176.28)	1.750 (44.45)	Call
MZ-450-250-6	A	4 1/2 (114)	2.50 (63.50)	6	4 1/2 (114.3)	3.250 (82.55)	6.94 (176.28)	1.750 (44.45)	Call
MZ-600-300-2	B	6 (152.40)	3.00 (76.20)	2	6 (152.40)	12.125 (307.98)	-	6.426 (163.22)	Call
MZ-600-300-4	B	6 (152.40)	3.00 (76.20)	4	6 (152.40)	12.125 (307.98)	-	6.426 (163.22)	Call
MZ-600-300-6	B	6 (152.40)	3.00 (76.20)	6	6 (152.40)	12.125 (307.98)	-	6.426 (163.22)	Call
MZ-600-400-2	B	6 (152.40)	4.00 (101.60)	2	6 (152.40)	12.125 (307.98)	-	6.426 (163.22)	Call
MZ-600-400-4	B	6 (152.40)	4.00 (101.60)	4	6 (152.40)	12.125 (307.98)	-	6.426 (163.22)	Call
MZ-600-400-6	B	6 (152.40)	4.00 (101.60)	6	6 (152.40)	12.125 (307.98)	-	6.426 (163.22)	Call



### Linear Motion Thimbles

The compact design and reliable operation of these linear motion thimbles allows precision linear probe positioning to distances up to 2 inches (50.8mm). Features include a clear bore design with a stainless steel welded bellows. The anodized aluminum collar is threaded to perform linear movement.

MODEL NUMBER	NOMINAL OD A	MINIMUM - MAXIMUM B	ID
LMT-133	1 1/4 (44.45)	1.800 - 2.800 (45.72 - 71.12)	0.54 (13.72)
LMT-275	3 1/4 (82.55)	3.060 - 5.060 (77.72 - 128.52)	1.43 (36.32)



### SPECIFICATIONS

#### Construction

Bellows: 1.04 to 4 inch (26.42 to 101.6mm)  
ID edge welded stainless steel

Base flange: 2 3/4 to 6 inch (70 to 152.4mm) CF, clearance holes

Traveling flange: 2 3/4 to 6 inch (70 to 152.4mm) CF, tapped holes

Guide rods: Dual 3/4 inch (19.05mm) OD hardened stainless steel

Stage: Aluminum

**Motion:** 2 to 6 inches (50.8 to 152.4mm) Z travel,  
Acme drive with position indicator scale

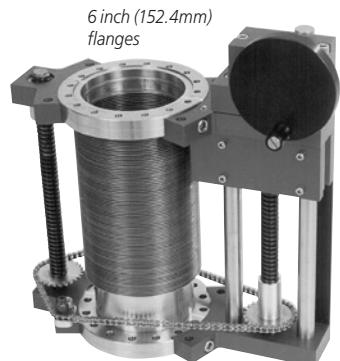
**Operating orientation:** Any

**Temperature**

Maximum bakeout: 150°C, fully assembled

Operating: 20°C (ambient)

**Vacuum range:** ≥ 10<sup>-10</sup> mbar (UHV)



### SPECIFICATIONS

#### Construction

Bellows: 0.54 or 1.43 inch (13.72 or 36.32mm)  
ID stainless steel

Flanges: 1 1/3 or 2 3/4 inch (34 or 70mm) CF, tapped holes

Collar: Anodized aluminum

**Motion:** Up to 2 inches (50.8mm) linear movement,  
360° graduations laser engraved on the collar

**Temperature range:** -20°C to 350°C

**Vacuum range:** ≥ 10<sup>-10</sup> mbar (UHV)



### SPECIFICATIONS

#### Construction

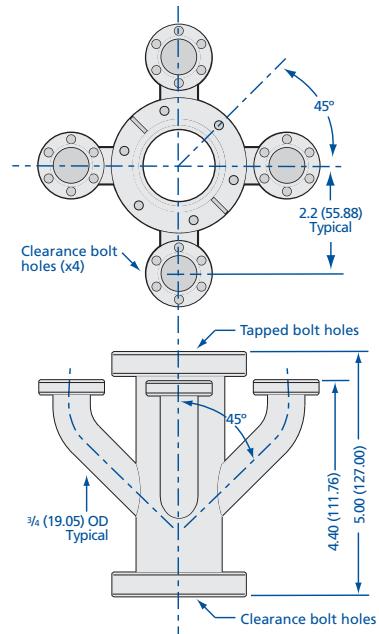
Material: 304 stainless steel  
Flanges: CF, tapped and clearance holes  
*see diagram for details*  
Finish: Electropolished

#### Operating orientation:

Any  
Temperature range: -200°C to 450°C  
Vacuum range:  $\geq 10^{-10}$  mbar (UHV)

### Utility Hat

Feedthroughs can be mounted to the base flange of the XYZ Manipulator or to a utility hat. A utility hat is the preferred method when X-Y movements of the sample will cause excessive flexing and abrading of utility lines in vacuum. The utility hat can be mounted between the precision rotary feedthrough and the traveling flange on top of the XYZ to provide X-Y movement of utility lines with the sample. Additionally, the utility hat can be used on top of a differentially pumped rotary seal to allow 360° polar rotation of utility lines along with the sample. (See photo next page.) The standard utility hat comes with a 1 $\frac{3}{4}$  inch (44.45mm) tube, two 2 $\frac{3}{4}$  inch (69.85mm) CF flanges and four 1 $\frac{1}{3}$  inch (34mm) CF ports for mounting feedthroughs. Standard finish is electropolish. Custom sizes can be supplied upon request.



**MODEL NUMBER**  
UH-175-2-133-4

### SPECIFICATIONS

#### Construction

Bellows: 1 $\frac{1}{2}$  inch (38.1mm) ID stainless steel  
Flanges: 2 $\frac{3}{4}$  inch (70mm) CF, tapped holes  
Pivots: Roller bearing

#### Motion:

$\pm 5^\circ$  XY adjustment range,  
knurled knob adjustment

#### Operating orientation:

Any

#### Temperature

Maximum bakeout: 200°C  
Operating: 20°C (ambient)

#### Vacuum range:

$\geq 10^{-10}$  mbar (UHV)

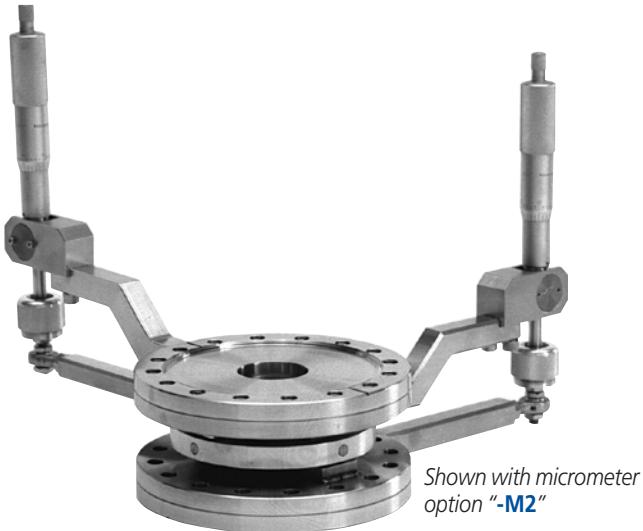
#### Options:

Micrometers “-M1” and “-M2”

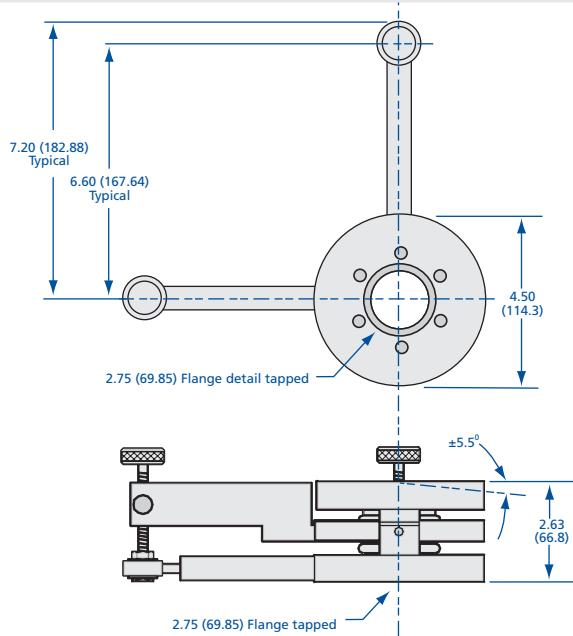
### Alignment Gimbals

Alignment gimbals allow a precise angle alignment to be established (and repeated) between two flanges. When the base flange of a gimbal is attached to the chamber flange (*or traveling stage of a positioning device*) and a probe is attached to the tilting flange, probe angle and tip position can be changed. Alignment gimbals were designed as an inexpensive method to align docking systems and actuate sample transfers. Gimbals cantilever the (horizontal) load when the linear feedthrough flange and the load lock are horizontally mounted and can also compensate for droop in long horizontal mounted linear feedthrough probes. Single axis alignment gimbals are also available. Call for pricing and availability.

MODEL NUMBER	DESCRIPTION
AG-275-150	Knurled knob adjustment on both axes
AG-275-150-M1	Micrometer adjustment on one axis, knurled knob on the other axis
AG-275-150-M2	Micrometer adjustment on both axes



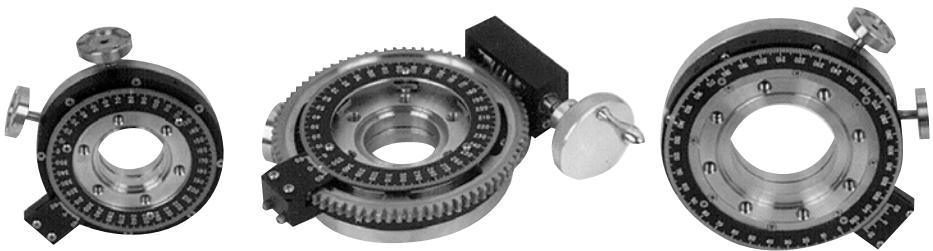
Shown with micrometer option “-M2”



# Sample Transfer & Manipulation

## Rotary Motion Feedthroughs

SECTION 9.6

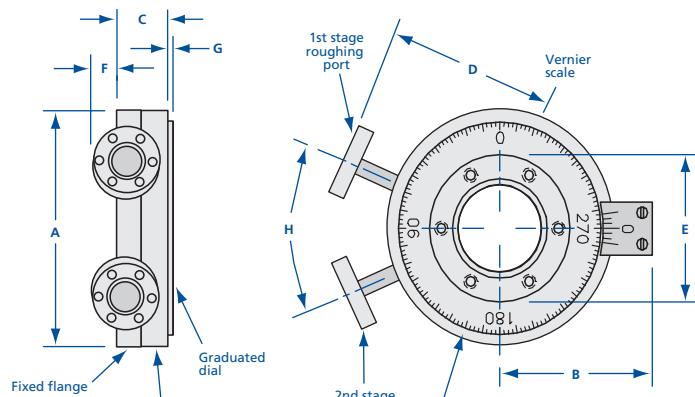


### Differentially Pumped Rotary Seals

Differentially pumped rotary seals provide 360° of continuous rotation through the vacuum wall of a UHV system. They have two stages of differential pumping isolated by graphite-impregnated, expanded, PTFE seals on special sealing surfaces. A pre-loaded ball bearing set accurately controls the rotating stage position, allowing the unit to be successfully used with manipulators and other precision positioning devices. For easier and more accurate angle adjustment, a worm drive fine adjust option is available. Rotary seals are also available with an anti-backlash stepping or synchronous motor drive. Sizes up to 4 inch (101.6mm) ID are standard, while larger sizes are available on request.

MODEL NUMBER	ID	NOMINAL OD	A	B	C	D	E	F	G	H	VERTICAL PAYLOAD*	HORIZONTAL PAYLOAD*
RS-150	1.53 (38.86)	2 <sup>3</sup> / <sub>4</sub> (69.85)	4.50 (114.30)	2.99 (75.95)	1.00 (25.40)	3.18 (80.77)	2.75 (69.85)	0.49 (12.45)	0.13 (3.30)	60°	54 (24.3)	30 (13.5)
RS-150-W	1.53 (38.86)	2 <sup>3</sup> / <sub>4</sub> (69.85)	5.13 (130.30)	3.38 (85.85)	1.00 (25.40)	4.95 (125.73)	2.75 (69.85)	0.49 (12.45)	0.37 (9.40)	60°	54 (24.3)	30 (13.5)
RS-250	2.53 (64.26)	4 <sup>1</sup> / <sub>2</sub> (114.3)	5.75 (146.05)	3.64 (92.46)	1.36 (34.54)	3.58 (90.93)	4.50 (114.30)	0.49 (12.45)	0.03 (0.76)	45°	90 (40.5)	38 (17.1)
RS-250-W	2.53 (64.26)	4 <sup>1</sup> / <sub>2</sub> (114.30)	6.38 (162.05)	4.20 (106.68)	1.36 (34.54)	6.11 (155.19)	4.50 (114.30)	0.49 (12.45)	0.41 (10.41)	45°	90 (40.5)	38 (17.1)
RS-400	4.03 (102.36)	6 (152.40)	7.75 (196.85)	4.57 (116.08)	1.68 (42.67)	4.34 (110.24)	6.02 (152.91)	0.37 (9.40)	0.06 (1.52)	45°	144 (64.8)	66 (29.7)
RS-400-W	4.03 (102.36)	6 (152.40)	8.50 (215.90)	8.25 (209.55)	1.68 (42.67)	9.28 (235.71)	6.02 (152.91)	0.37 (9.40)	0.54 (13.72)	45°	144 (64.8)	66 (29.7)

\*Note: Standard maximum payloads with center of gravity within 10% of the RS ID from the RS centerline when vertical, within one ID of the RS from the RS flange face when horizontal, and certain other size restrictions are met – consult factory.



### SPECIFICATIONS

#### Construction

Flanges: CF, tapped holes, one rotational and one stationary  
T-wrench included for adjustment

Motion: 360° rotation, two stage, differentially pumped with 360° vernier scale

Operating orientation: Any

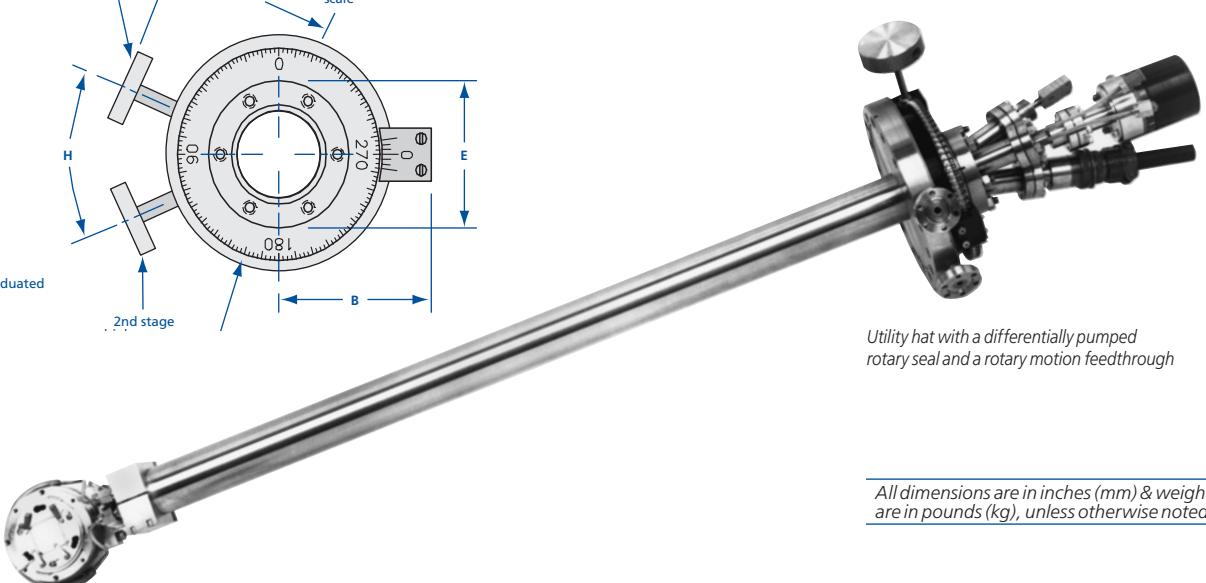
#### Temperature

Maximum bakeout: 150°C  
Operating: 20°C (ambient)

Vacuum range: ≥ 10<sup>-11</sup> mbar (UHV)

Readability: Standard scale 1.0°, mechanical counter 0.1°, micro-stepped motor drive required for maximum resolution

Options: Fine adjust worm drive “-W”, digital counters, stepper motors and other sizes available



Utility hat with a differentially pumped rotary seal and a rotary motion feedthrough

All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.



# Sample Transfer & Manipulation

## Rotary Motion Feedthroughs

### SPECIFICATIONS

#### Construction

Mounting flange:  $2\frac{3}{4}$  (70mm) CF, clearance holes

Rotary probe:  $\frac{3}{8}$  inch (9.53mm)

Drive: Motor drive with controller, manual drive knob with position lock

Bearings: 4,000,000 revolutions before service

**Motion:** 360° continuous with variable speed

**Operating orientation:** Any

#### Temperature

Maximum bakeout: 200°C, with drive removed  
Operating: 20°C (ambient)

**Vacuum range:**  $\geq 10^{-10}$  mbar (UHV)

#### Torque

Motor: 50 ounce-inches (.353 Nm)

Feedthrough: 150 ounce-inches (1.059 Nm)

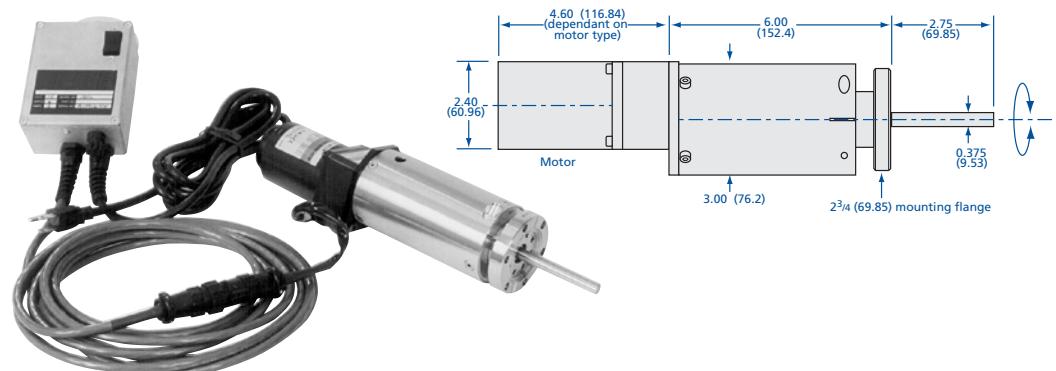
**Speed:** 5 to 95 RPM

**Options:** Higher torque motors, different speed ranges

### Motorized Rare Earth Magnetic Rotary Motion Feedthrough

The rare earth magnetic series rotary drives are designed to provide exceptional, long life performance. They are UHV compatible and are an excellent option to conventional bellows sealed and other rotary devices. They can be adapted to pulsed laser deposition (PLD) target clocking and continuous rotation of targets and substrates, as well as applications that require small profiles and high performance. There are no sliding seals or magnets in vacuum and stray magnetic fields are virtually nonexistent. The in-vacuum armature is made of paramagnetic materials with stainless steel and silicon nitride bearings and is capable of repeated bake-out to 200°C with magnets removed. Out-of-vacuum bearings are accessible for lubrication and the magnet drive is easily removable.

MODEL NUMBER	FLANGE TYPE	SHAFT OD	SHAFT LENGTH
MRRE-275-038	2.75 CF	0.375 (9.53)	2.75 (69.85)



### SPECIFICATIONS

#### Construction

Mounting flange:  $1\frac{1}{3}$  or  $2\frac{3}{4}$  (34 or 70mm) CF, clearance holes

Rotary shaft:  $\frac{1}{4}$  inch (6.35mm)

Drive: Manually actuated

Attachment: 8-32 tapped hole

**Motion:** 360° continuous, with 360° graduations on knob and locking screw

**Operating orientation:** Any

**Temperature range:** -20°C to 150°C

**Vacuum range:**  $\geq 10^{-10}$  mbar (UHV)

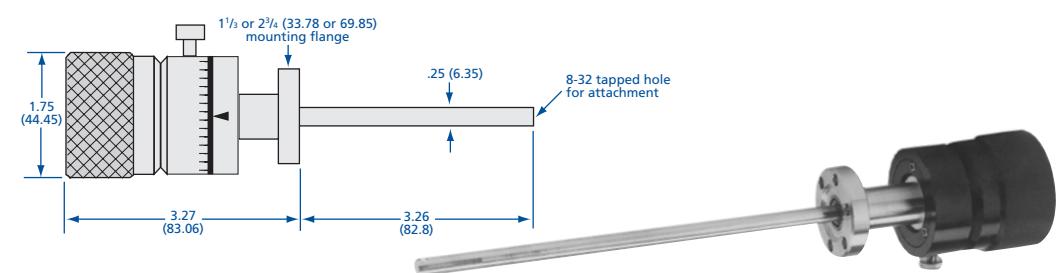
**Torque:** 50 ounce-inches (.353 Nm)

**Options:** Tapped holes, special lengths

### 1/4 Inch Precision Rotary Motion Feedthroughs

Precision rotary feedthroughs provide 360° continuous rotation and may be used to define a polar axis for a sample or probe or to actuate a mechanical device, such as a shutter, inside the vacuum chamber. Typically used for polar rotation on top of an XYZ manipulator.

MODEL NUMBER	FLANGE TYPE	SHAFT OD	SHAFT LENGTH
PRM-133	1.33 CF	0.25 (6.35)	3.26 (82.80)
PRM-275	2.75 CF	0.25 (6.35)	3.26 (82.80)



### SPECIFICATIONS

#### Construction

Bellows: Welded stainless steel

Mounting flange:  $2\frac{3}{4}$  (70mm) CF, clearance holes

Rotary shaft:  $\frac{3}{8}$  inch (9.53mm)

Drive: Manually actuated

**Motion:** 360° continuous, 0.10° resolution (1° graduations on dial), maximum run-out 0.005 inches (.13mm)

**Operating orientation:** Any

#### Temperature

Maximum bakeout: 200°C  
Operating: 20°C (ambient)

**Vacuum range:**  $\geq 10^{-10}$  mbar (UHV)

**Torque:** 1,100 ounce-inches (7.768 Nm)

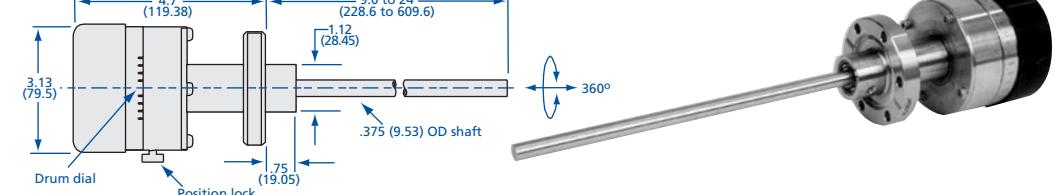
**Options:** Custom shaft lengths: 9 to 23 inches (228.6 to 584.2mm).

Change model number suffix **-24**. Additional charges will apply. Example: PRM-275-038-12 (indicates 12 inch (304.8mm) shaft), field-mountable shaft extensions, fine adjust and motor drives

### 3/8 Inch Precision Rotary Motion Feedthrough

Precision rotary feedthroughs are commonly used to define a polar axis for a sample or probe. They provide 360° continuous rotation and are mounted on top of XYZ manipulators and other stages. They are also used separately where precision angular orientation is needed.

MODEL NUMBER	FLANGE TYPE	SHAFT OD	SHAFT LENGTH
PRM-275-038-24	2.75 CF	$\frac{3}{8}$ (9.53)	24.00 (609.60)



# Sample Transfer & Manipulation

## Linear Motion Feedthroughs

SECTION 9.6

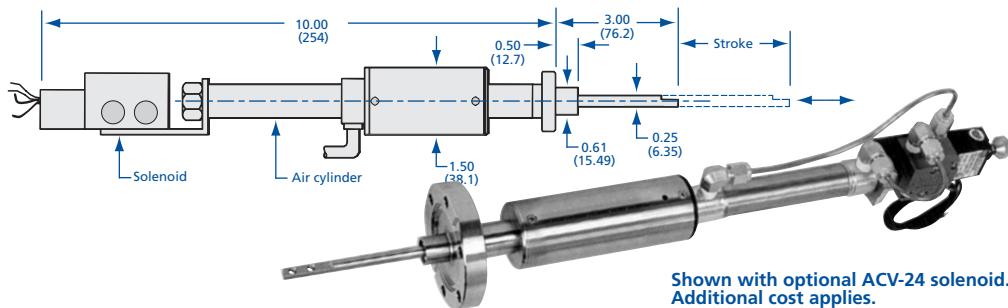


### Pneumatically Actuated Linear Motion Feedthrough

Commonly used as positioning devices for shutters and beam stoppers.

MODEL NUMBER	FLANGE TYPE	SHAFT OD	TRAVEL
ALM-133-2	1.33 CF	0.25 (6.35)	2 (50.80)
ALM-133-4	1.33 CF	0.25 (6.35)	4 (101.60)

#### ACV-24 Solenoid

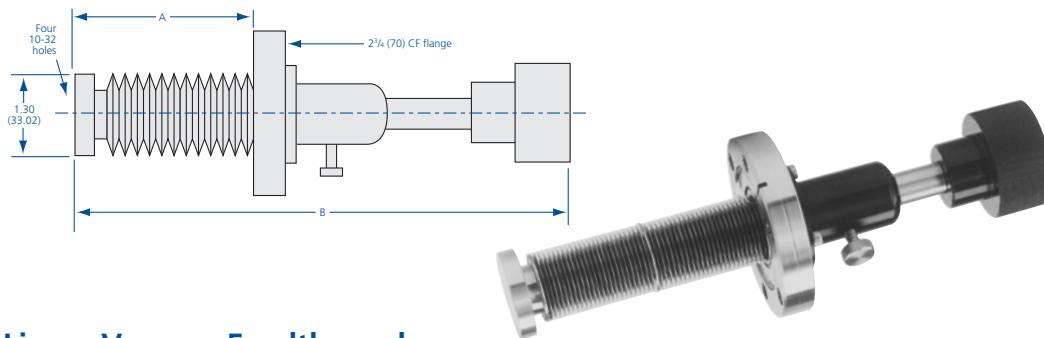


Shown with optional ACV-24 solenoid.  
Additional cost applies.

### Heavy-Duty Push-Pull Linear Motion Feedthroughs

Manually operated linear motion positioning device designed for UHV applications.

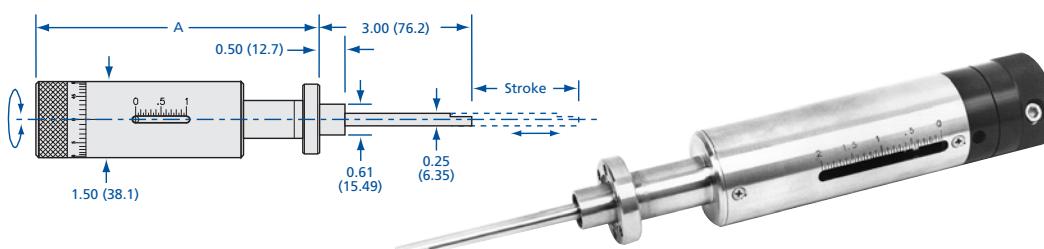
MODEL NUMBER	FLANGE TYPE	TRAVEL	MINIMUM - MAXIMUM A	B
HLM-275-2	2.75 CF	2 (50.80)	1.1 - 3.1 (27.94 - 78.74)	6.75 (171.45)
HLM-275-3	2.75 CF	3 (76.20)	1.4 - 4.4 (35.56 - 111.76)	8.07 (204.98)
HLM-275-4	2.75 CF	4 (101.60)	1.7 - 5.7 (43.18 - 144.78)	9.38 (238.25)



### Linear Vacuum Feedthrough

Manually operated linear motion positioning device with rotary actuation.

MODEL NUMBER	FLANGE TYPE	LINEAR TRAVEL	SHAFT OD
RLM-133-2	1.33 CF	2 (50.80)	0.25 (6.35)
RLM-133-4	1.33 CF	4 (101.60)	0.25 (6.35)
RLM-275-2	2.75 CF	2 (50.80)	0.25 (6.35)
RLM-275-4	2.75 CF	4 (101.60)	0.25 (6.35)



#### SPECIFICATIONS

##### Construction

Bellows: Welded stainless steel, sealed  
Mounting flange: 1 1/3 (34mm) CF, clearance holes  
Linear probe: 1/4 inch (6.35mm) OD  
Cylinder: 3/4 inch (19.05mm) ID  
Bushing: Macor

##### Motion

Linear: 2 to 4 inch (50.8 to 101.6mm) travel,  
pneumatically actuated  
Operating air pressure: 50 to 150 psi

##### Operating orientation:

Any

##### Temperature

Maximum bakeout: 200°C

Operating: 20°C (ambient)

##### Vacuum range:

≥ 10<sup>-10</sup> mbar (UHV)

##### Options:

2 3/4 inch (69.85) OD flange, solenoid

24VDC or per customer requirements

#### SPECIFICATIONS

##### Construction

Bellows: Welded stainless steel, sealed  
Mounting Flange: 2 3/4 (70mm) CF, clearance holes

##### Motion:

2, 3 and 4 inch (50.08, 76.2 and 101.6mm)

##### Operating orientation:

Any

##### Temperature range:

-20°C to 250°C

##### Vacuum range:

≥ 10<sup>-10</sup> mbar (UHV)

##### Maximum lateral load:

20 pounds

#### SPECIFICATIONS

##### Construction

Bellows: Welded stainless steel, sealed  
Mounting flange: 1 1/3 or 2 3/4 (34 or 70mm) CF, clearance holes  
Linear shaft: 1/4 inch (6.35mm) OD  
Drive: All ball bearing

##### Motion:

2 or 4 inch (50.8 or 101.6mm) linear travel,  
20 turns/inch (25.4) rotary actuation, position indicator

##### Operating orientation:

Any

##### Temperature

Maximum bakeout: 200°C

Operating: 20°C (ambient)

##### Vacuum range:

≥ 10<sup>-10</sup> mbar (UHV)

##### Options:

Longer strokes

All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.

# 9 SECTION 9.6 Sample Transfer & Manipulation

## Linear/Rotary Motion Feedthroughs

### SPECIFICATIONS

#### Construction

Mounting flange:  $2\frac{3}{4}$ (70mm) CF, clearance holes  
Probe:  $\frac{1}{2}$  inch (12.7mm) OD stainless steel tubular probe  
Drive: Removable neodymium iron boron magnet  
Bearings: 8 stainless steel

#### Motion

Linear: 24 and 36 inch (609.6 and 914.4mm), adjustable stops  
Rotary:  $360^\circ$  continuous rotation, with  $0^\circ$  to  $360^\circ$  indication

#### Operating orientation:

Horizontal  
Maximum temperature:  $200^\circ\text{C}$  with drive removed

Vacuum range:  $\geq 10^{-10}$  mbar (UHV)

Linear force: 4 pounds (1.8 kg)

Torque: 150 ounce-inches (1.059 Nm)

Options: Light-touch magnet (-LT)

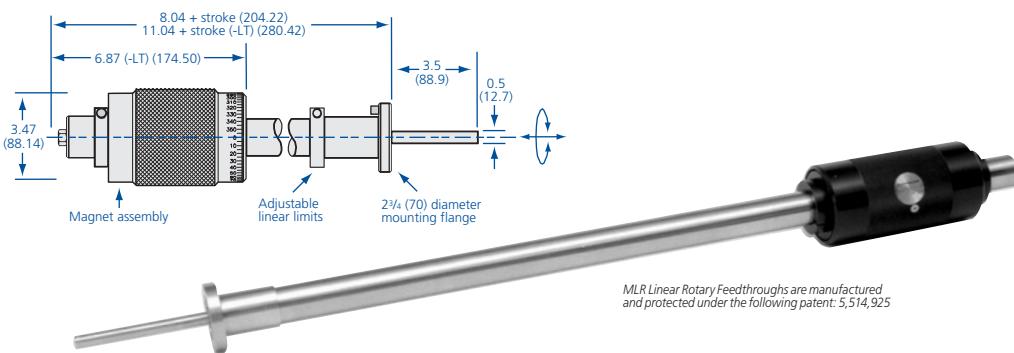
### Magnetic Linear/Rotary Feedthrough

Magnetically coupled feedthroughs offer exceptional linear/rotary motion for short to medium stroke sample introduction and transfer of light loads. The standard magnetic driver package provides more than 150 ounce-inches (1.059 Nm) of torque and four pounds of linear force. The inside traveler has no magnets, but it is made of magnetically permeable material.

### LIGHT-TOUCH MAGNET ASSEMBLY OPTION (-LT)

- Utilizes dynamically loaded full-bearing support to increase tactile feedback
- Heavy-duty linear magnet driver increases linear force to 15 pounds (6.75 kg)

MODEL NUMBER	DESCRIPTION
MLR-275-050-24	24 inch (609.6) stroke
MLR-275-050-36	36 inch (914.4) stroke
-LT	Light-touch magnet assembly option (Add -LT to the model number)



### SPECIFICATIONS

#### Construction

Mounting flange:  $2\frac{3}{4}$ (70mm) CF, clearance holes  
Linear shaft:  $\frac{3}{4}$  inch (19.05mm)  
Rotary probe:  $\frac{1}{4}$  inch (6.35mm)  
Drive: Removable neodymium iron boron magnet  
Bearings: Precision internal guide

#### Motion

Linear: Up to 48 inch (1219.2mm)  
Rotary:  $360^\circ$  continuous

#### Operating orientation:

Horizontal  
Temperature

Maximum bakeout:  $200^\circ\text{C}$ , drive removed  
Operating:  $20^\circ\text{C}$  (ambient)

Vacuum range:  $\geq 10^{-10}$  mbar (UHV)

Linear force: 15 pounds (6.75 kg)

Torque: 150 ounce-inches (1.059 Nm)

Options: Soft-touch magnet (-ST)

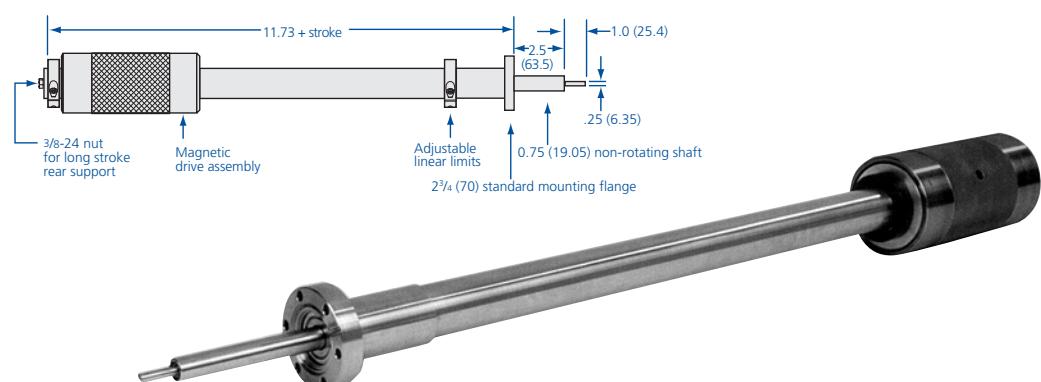
### Coaxial Magnetic Linear/Rotary Feedthrough

Magnetically-coupled linear/rotary feedthroughs offer unparalleled smooth rotary motion for medium to long stroke sample introduction and transfer of light loads. The coaxial design features a  $\frac{3}{4}$  inch (19.05mm) linear support tube with rotary bearing in the tip to guide the  $\frac{1}{4}$  inch (6.35mm) rotary probe. In addition to rotary motion, the design includes a linear driver, for additional axial force and tactile feedback.

### SOFT-TOUCH MAGNET ASSEMBLY OPTION (-ST)

- Soft touch magnet assembly utilizes dynamically loaded full-bearing support to increase tactile feedback.

MODEL NUMBER	DESCRIPTION
MLRC-275-36	36 inch (914.4) stroke
MLRC-275-42	42 inch (1066.8) stroke
MLRC-275-48	48 inch (1219.2) stroke
-ST	Soft-touch magnet assembly option (Add -ST to model number)



All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.

# Sample Transfer & Manipulation

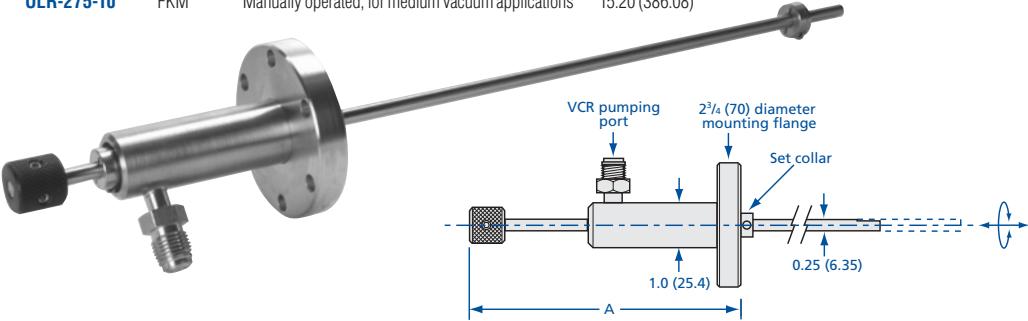
## Linear/Rotary Motion Feedthroughs

SECTION 9.6



### Differentially Pumped Linear/Rotary Motion Feedthrough

MODEL NUMBER	SEAL	DESCRIPTION	MAXIMUM A
OLR-275-10	FKM	Manually operated, for medium vacuum applications	15.20 (386.08)



#### SPECIFICATIONS

##### Construction

Feedthrough: stainless steel  
Mounting flange: 2 3/4 (70mm) CF, clearance holes  
Probe: 1/4 inch(6.35mm) OD  
Seal: Differentially pumped FKM O-ring  
Body insert: PTFE

##### Motion

Linear: 10 inch (254mm), clamp type stop collar  
Other lengths available on request.  
Rotary: 360° continuous rotation

##### Operating orientation:

Any

##### Temperature range:

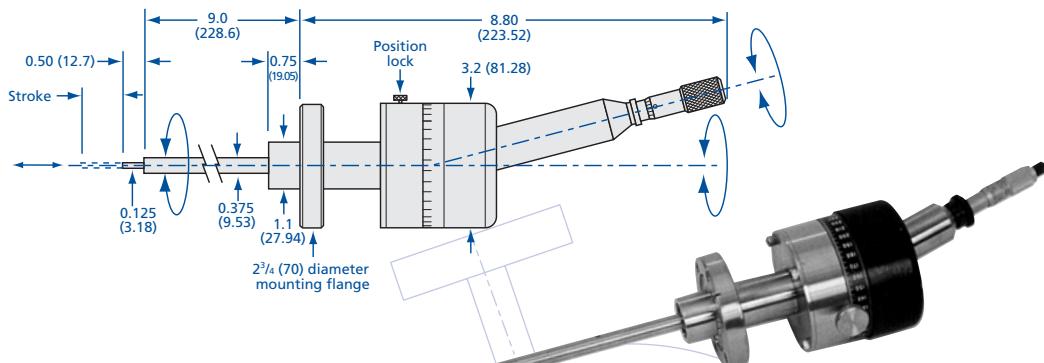
-20°C to 150°C

##### Vacuum range:

≥ 10<sup>-5</sup> mbar (Medium vacuum)

### Precision Linear/Rotary Motion Feedthrough

MODEL NUMBER	DESCRIPTION	STROKE
PLR-275-050	Stand-alone device or used when coupled with a gearbox to control polar and azimuthal rotation of a sample	1/2 (12.70)



#### SPECIFICATIONS

##### Construction

Mounting flange: 2 3/4 (70mm) CF, clearance holes  
Linear probe: 1/8 inch (3.18mm) OD  
Rotary tube: 3/8 inch (9.53mm) OD,  
9 inch (228.6mm) length  
Bearings: Precision internal guide

##### Motion

Linear: 1/2 inch (12.7mm), micrometer adjusted  
Rotary: 360° continuous, 0.1° resolution  
in 1.0° graduations with position lock

##### Operating orientation:

Any

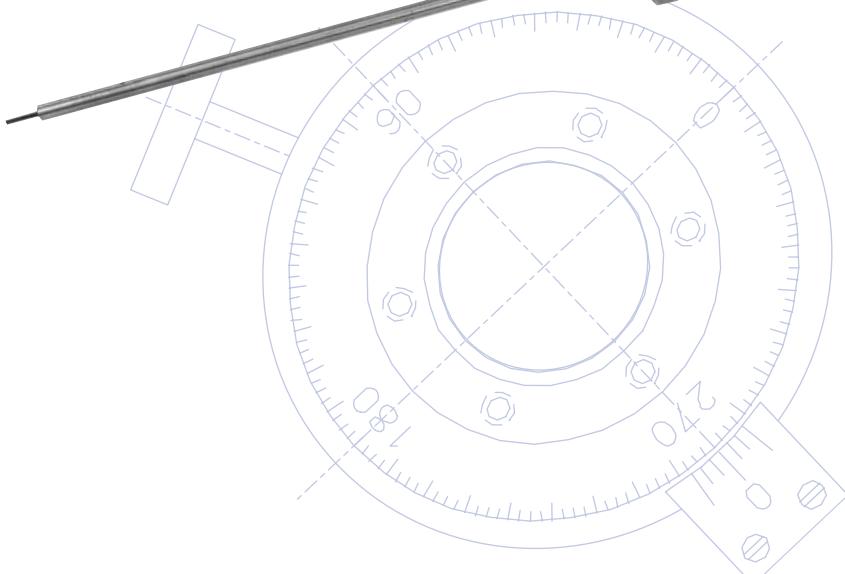
##### Temperature

Maximum bakeout: 200°C

Operating: 20°C (ambient)

##### Vacuum range:

≥ 10<sup>-8</sup> mbar (UHV)



All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.



### SPECIFICATIONS

#### Construction

Bellows: Welded stainless steel  
Mounting flange: CF or NW  
Shaft OD:  $\frac{1}{8}$  or  $\frac{1}{4}$  inch (3.18 or 6.35mm)  
Drive: Manually actuated

#### Motion:

$\pm 22^\circ$  or  $\pm 30^\circ$  tilt

#### Operating orientation:

Any

#### Temperature range

Metal seal: 450°C

Elastomerseal: 200°C

#### Vacuum range

Metal seal:  $\geq 10^{-10}$  mbar (UHV)

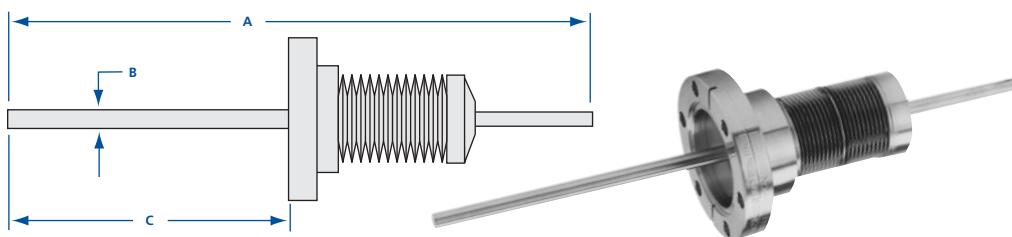
Elastomerseal:  $\geq 10^{-8}$  mbar (High Vacuum)

## Wobble Sticks

WBL wobble sticks offer a simple means of positioning samples in vacuum by permitting Z-axis and tilt movements. All stainless steel construction designed for use in high vacuum or UHV environments.

MODEL NUMBER	FLANGE TYPE	FLEX ANGLE*	A	B	MIN. - MAX. C
WBL-133	1.33 CF	$\pm 22^\circ$	6 (152.40)	0.12 (3.05)	3 - $3\frac{1}{2}$ (76.20 - 88.90)
WBL-275	2.75 CF	$\pm 30^\circ$	10 (254.00)	0.25 (6.35)	$3\frac{3}{4}$ - 6 (95.25 - 152.40)
WBL-NW-16	NW-16	$\pm 22^\circ$	6 (152.40)	0.12 (3.05)	3 - $3\frac{1}{2}$ (76.20 - 88.90)
WBL-NW-40	NW-40	$\pm 30^\circ$	10 (254.00)	0.25 (6.35)	$3\frac{3}{4}$ - 6 (95.25 - 152.40)

\* Mating flange may restrict flexible angle



### SPECIFICATIONS

#### Construction

Bellows: Welded stainless steel, independent for Z and theta

Mounting flange:  $2\frac{3}{4}$  (70mm) CF, clearance holes

Tip: Pre-fitted with hook

Drive: Manually actuated

#### Motion

Rotary: 360° probe rotation via rotary motion feedthrough

Linear: 4 or 8 inch (101.6 or 203.2mm) stroke

Tilt:  $\pm 22^\circ$

#### Operating orientation:

Any

#### Temperature

Maximum bakeout: 200°C

Operating: 20°C (ambient)

#### Vacuum range:

$\geq 10^{-10}$  mbar (UHV)

#### Options:

Single-jaw pincer (add "-PS" to model number), double-jaw and other pincers upon request

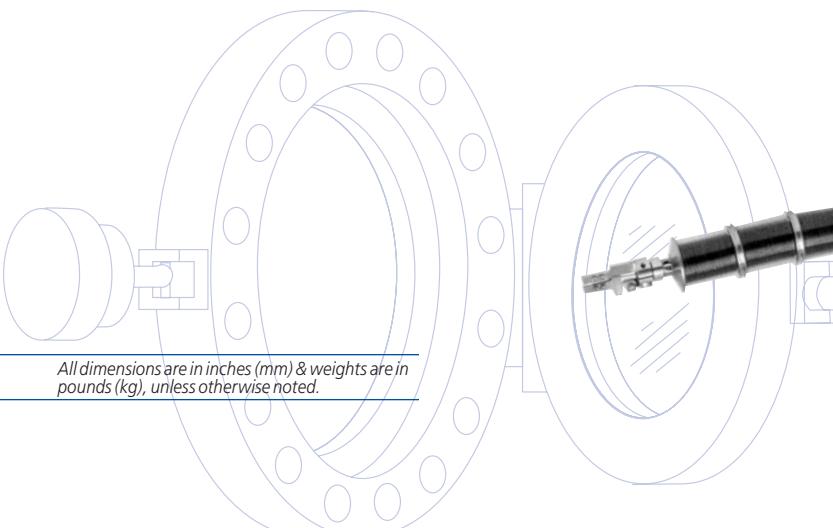
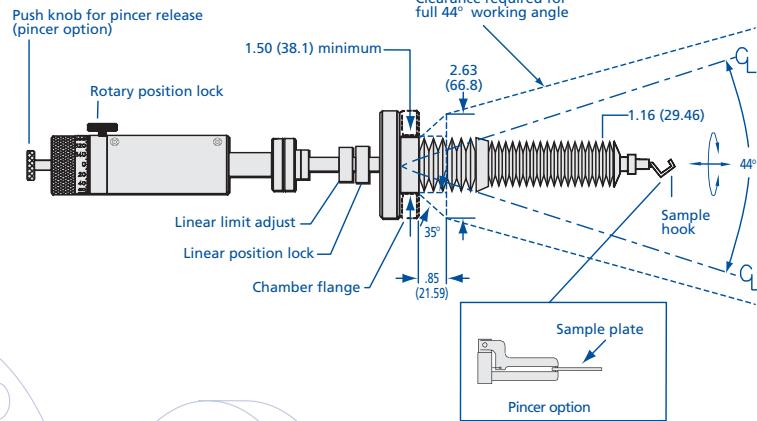
## Rotary Wobble Sticks

RWS wobble sticks provide Z-axis, polar rotation, and polar axis tilt to allow tip positioning inside a vacuum chamber. They offer an inexpensive alternative for sample introduction and manipulation.

MODEL NUMBER	FLANGE TYPE	FLEX ANGLE*	Z STROKE
RWS-275-4	2.75 CF	$\pm 22^\circ$	4 (101.60)
RWS-275-8	2.75 CF	$\pm 22^\circ$	8 (203.20)

-PS Single Jaw Pincer Option Add -PS to model number

\* Mating flange may restrict flexible angle



All dimensions are in inches (mm) & weights are in pounds (kg), unless otherwise noted.